

IMPLEMENTATION OF LOAD FOLLOWING IN MULTI AREA HYDROTHERMAL SYSTEM UNDER RESTRUCTURED ENVIRONMENT

A. Suresh Babu¹, Ch.Saibabu², S.Sivanagaraju³

¹Department of EEE, SSN Engineering College, Andhra Pradesh, India
asbabueee@gmail.com

²Department of EEE, J.N.T University, Kakinada, Andhra Pradesh, India.
chs_eee@yahoo.com

³Department of EEE, J.N.T University, Kakinada, Andhra Pradesh, India.
sirigiri70@yahoo.co.in

ABSTRACT

This paper presents the method in implementing the concept of load following adapted in an Automatic Generation Control (AGC) under restructured scenario. Open transmission access and the evolving of more socialized companies for generation, transmission and distribution affects the formulation of AGC problem. To accommodate new constraints associated with territorial of the traditional AGC two area system is modified to take into account the role of AGC in open market system. This paper investigates the performance of a load following controller on each generator involved in bilateral contracts. A suitable control strategy is also proposed for the generators taking part in load following to share a portion of the uncontracted power demanded by the customers. The concept of Disco Participation is employed and reflected in the two-area block diagram. The proposed system is tested for a two area hydrothermal system considering without and with contract violation. Simulation results show that the concept of load following is successfully implemented in the system

KEYWORDS

Automatic Generation Control, Load Following, Hydrothermal system, Disco Participation Matrix

I. INTRODUCTION

Successful operation of a power system is the process of properly maintaining several sets of balances. Two of these balances are between load-generation and scheduled and actual tie line flows. These two balances are predominant factors to keep frequency constant. Constant frequency is identified as the primary index of healthy operation of system and the quality of supplied power to consumer as well. Both of these balances are maintained by adjusting generation keeping load demand in view. If frequency is low, generation is increased and if the actual outflow is greater than the scheduled outflow, generation is decreased. Since system conditions are always changing as load constantly varies during different hours of a day, precise manual control of these balances would be impossible. Automatic Generation Control (AGC) was developed to both maintain a (nearly) constant frequency and to regulate tie line flows [1-3]. Under open market system (deregulation) the power system structure changed in such a way that would allow the evolving of more specialized industries for generation (Genco), transmission (Transco) and distribution (Disco). A detailed study on the control of generation in deregulated power systems is given in [4]. The concept of independent system operator (ISO) as an unbiased coordinator to balance reliability with economics has also emerged [5-

6]. The assessment of Automatic Generation control in a deregulated environment is given in detail in [7-8] and also provides a detailed review over this issue and explains how an AGC system could be simulated after deregulation. A modified AGC schemes have been proposed for frequency regulation and load following as well [9-11]. A practical AGC model to cater the needs of a modern deregulated hydro-thermal system is discussed in detail in [12-13]. In view of this the main objectives of the present paper are the following:-

1. To consider an interconnected hydrothermal system in continuous mode strategy and to evaluate dynamic responses considering conventional integral controllers in both areas.
2. To implement the bilateral contracts into the thermal system thus designing the system under open market scenario.

This paper organized as follows. Dynamic mathematical model of two area system is described in section 2. Modified two area model is presented in Section 3. Section 4 covers simulated results and discussion and finally conclusion is given section 5.

II. DYNAMIC MATHEMATICAL MODEL

Electric power systems are complex and nonlinear dynamic systems. The Automatic generation controller controls the control valves associated with High Pressure (HP) turbine at very small load variations. The system under investigation has tandem-compound single reheat type thermal system. Each element (Governor, turbine and power system) of the system is represented by first order transfer function at small load variations in according to the IEEE committee report [8]. Two system nonlinearities likely Governor Deadband and Generation Rate Constraint (GRC) are considered here for getting the realistic response. Governor Deadband is defined as the total magnitude of the sustained speed change within which there is no change in the valve position [8]. It is required to avoid excessive operation of the governor. GRC is considered in real power systems because there exits a maximum limit on the rate of change in the generating power. Figure 1 shows the transfer function block diagram of a two area interconnected network .The parameters of two area model are defined in Appendix.

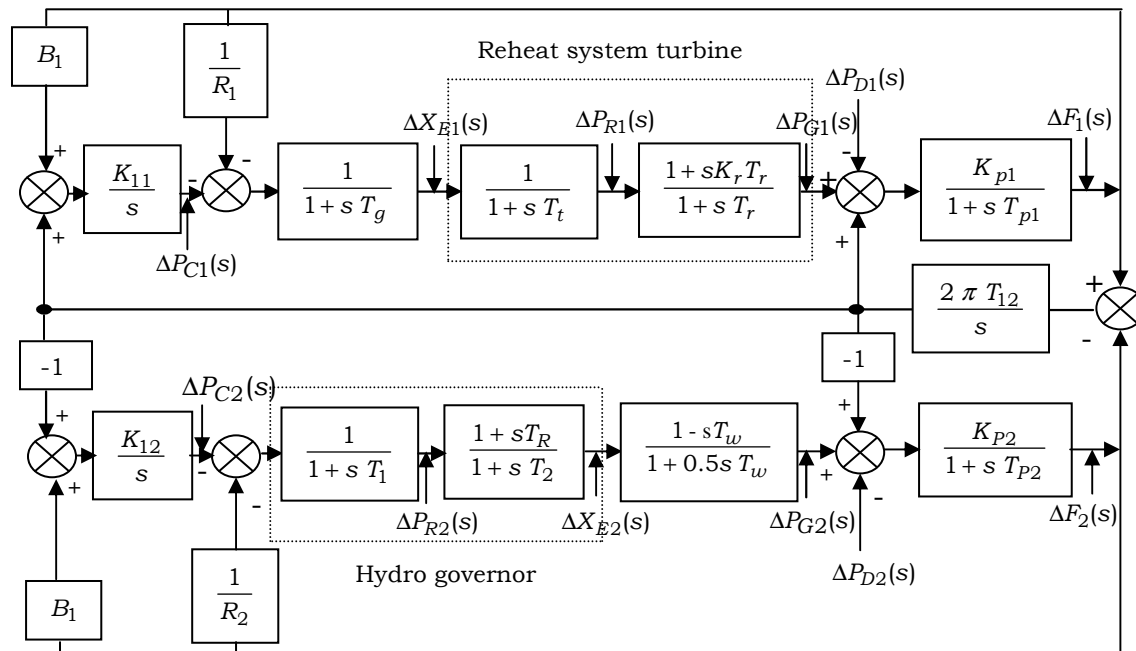


Figure 1. Two Area Hydrothermal System

III. FORMULATION OF BLOCK DIAGRAM

In the restructured environment, Gencos sell power to various Discos at competitive prices. Thus, Discos have the liberty to choose the Gencos for contracts. They may or may not have contracts with

the Gencos in their own area. This makes various combinations of Genco-Disco contracts possible in practice. The concept of a “Disco Participation Matrix” (DPM) is considered to make the visualization of contracts easier. DPM is a matrix with the number of rows equal to the number of Gencos and the number of columns equal to the number of Discos in the system. Each entry in this matrix can be thought of as a fraction of total load contracted by a Disco (Column) towards a Genco (row). Thus, the ij^{th} entry corresponds to the fraction of the total load power contracted by Disco ‘j’ from a Genco ‘i’. The sum of all the entries in a Column in this matrix is unity. DPM shows the participation of a Disco in a contract with Genco; hence the name “Disco Participation Matrix”. DPM shows the participation of a Disco in a contract with any Genco, hence the name Disco Participation Matrix. Whenever a load demanded by a Disco changes it is reflected as a local load in the area to which this Disco belongs. This corresponds to the local loads ΔP_{L1} and ΔP_{L2} which should be reflected in the deregulated AGC system block diagram at the point of input to the power system block.

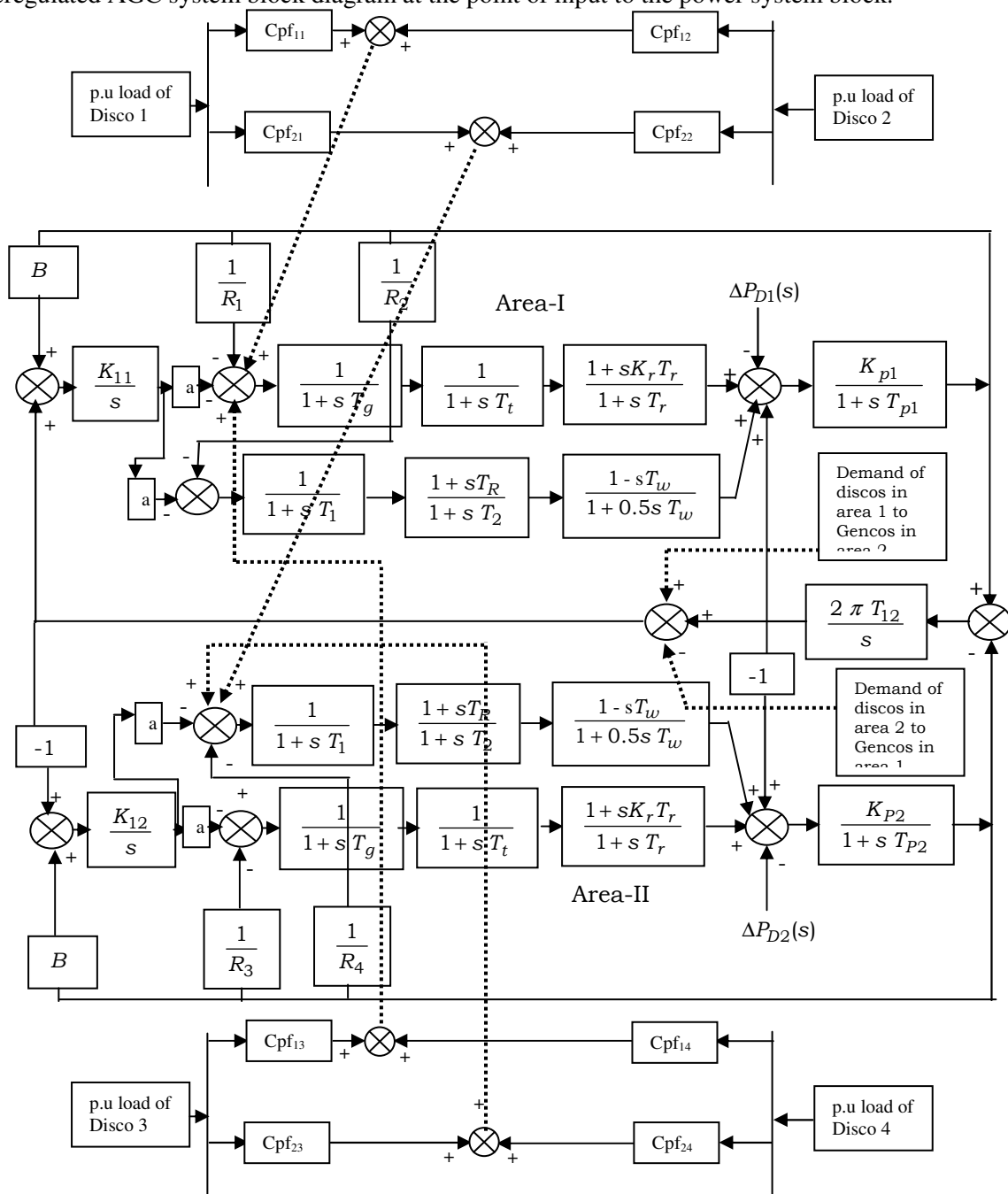


Figure. 2. Two area Hydro-thermal system under Load following of restructured environment

As there are many Gencos in each area, Area Control Error signal has to be distributed among them in proportion to their participation in the AGC. Coefficients that distribute ACE to several Gencos are termed as “ACE participation factors” (apfs). It should be noted that $\sum_{j=1}^m apf_j = 1$ where m is the number

of Gencos. Unlike in the traditional AGC system a Disco demands a particular Genco for load power. These demands must be reflected in the dynamics of the system. Turbine and governor units must respond to this power demand. Thus as a particular set of Gencos are supposed to follow the load demanded by a Disco, information signals must flow from a Disco to the particular Genco specifying corresponding demands. The demands are specified by cpf’s (elements of DPM) and the p.u MW load of a Disco. These signals carry information as to which Genco has to follow a load demanded by which Disco. The scheduled steady state power flow on the tie line is given as

$$\Delta P_{tie12,scheduled} = (\text{demand of Discos in area 1 to Gencos in area 2}) - (\text{demand of Discos in area 2 to Gencos in area 1})$$

At any time the tie line power error $\Delta P_{tie12,error}$ is defined as

$$\Delta P_{tie12,error} = \Delta P_{tie12,actual} - \Delta P_{tie12,scheduled} \tag{1}$$

$\Delta P_{tie12,error}$ vanishes in the steady state as the actual tie line power flow reaches the scheduled power flow. This error signal is used to generate the respective ACE signals as in the traditional scenario. In the steady state the generation of each Genco matches the demand of Discos in contract with it. For example if a Disco ‘d’ demands 1p.u MW from Genco 1 then at the steady state it would generate as follows

$$\sum_{d=1}^n (\text{p.u_ MW load of Disco ‘d’}) \times cpf_{1d} = 1\text{p.u MW} \tag{2}$$

Contract Violation

It may happen that a Disco may violate a contract by demanding more than that specified in the contract. This excess power is not contracted out to any Genco. This uncontracted power must be supplied by the Gencos in the same area as that of the Disco. It must be reflected as a local load of the area but not as the contract demand.

IV. RESULTS AND DISCUSSIONS

Simulation studies are performed to investigate the performance of the two-area hydrothermal system under deregulated Environment. Here in the two-area hydrothermal system three Gencos and two Discos are considered in each area. It is assumed in this work that one Genco in each area is under AGC only and the remaining Gencos participate in the bilateral contracts. It is assumed that there is 0.2% step load disturbance of each Disco, as a result of which the total step load disturbance in each area and accounts to 0.4% and each Genco participates in AGC as defined by following area participation factors (apfs):

$apf_1=0.25, apf_2=0.25, apf_3=0.5, apf_4=0.25, apf_5=0.25, apf_6=0.5$ and the Discos contract with the Gencos as per the following Disco Participation Matrix

$$DPM = \begin{bmatrix} 0.25 & 0.3 & 0.1 & 0.3 \\ 0.25 & 0.1 & 0.4 & 0.4 \\ 0 & 0 & 0 & 0 \\ 0.25 & 0.4 & 0.3 & 0.1 \\ 0.25 & 0.2 & 0.2 & 0.2 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

As mentioned earlier in the steady state, theoretically the Gencos must generate

$$\Delta P_{g1} = 0.25 \times 0.002 + 0.3 \times 0.002 + 0.1 \times 0.002 + 0.3 \times 0.002 = 0.0019$$

Where 0.002 is the 0.2% step load disturbance of respective Disco. Similarly

$$\Delta P_{g2} = 0.0023 \text{ p.u} ; \Delta P_{g3} = 0.0 \text{ p.u} ; \Delta P_{g4} = 0.0021 \text{ p.u} ; \Delta P_{g5} = 0.0017 \text{ p.u} ; \Delta P_{g6} = 0.0 \text{ p.u}$$

A nominal value of 0.5 is considered for the gain setting of integral controller in both the areas. Table 1 gives the error between the theoretical and simulated values of generation for the above case.

Table 1 Error value between theoretical and simulated values

	Type of Genco	Theoretical Values	Simulated Values	Error
Area 1	Genco 1	0.0019	0.00209	-0.0001
	Genco 2	0.0023	0.00209	0.0003
	Genco 3	0.0	0	0
Area 2	Genco 4	0.0021	0.002131	-0.00003
	Genco 5	0.0017	0.00179	-0.00009
	Genco 6	0.0	0.0	0

Where $Error = Theoretical\ values - Simulated\ Values$

Contract violation case has also been considered in this work. In this case it is considered that Disco₁ demands additional load of 0.3% after 30 sec and Disco₄ in area 2 demands additional load of 0.3% after 60 sec. It can be seen that the uncontracted power is supplied by the Gencos in the same area as that of the Disco which has demanded for additional power. Table 2 gives the generations of Gencos during contract violation.

Table 2 Generation of Gencos during contract violation

	Type of Genco	Simulated Values
Area 1	Genco 1	0.00333
	Genco 2	0.00333
	Genco 3	0.00062
Area 2	Genco 4	0.00326
	Genco 5	0.0030
	Genco 6	0.00065

Figures 3-6 show the variation of frequency deviation of both areas, tie line power error deviation and generation of Gencos of both areas during the base case. Figures 7-10 show the variation of frequency deviation of both areas, tie line power error deviation and generation of Gencos of both areas during the contract violation

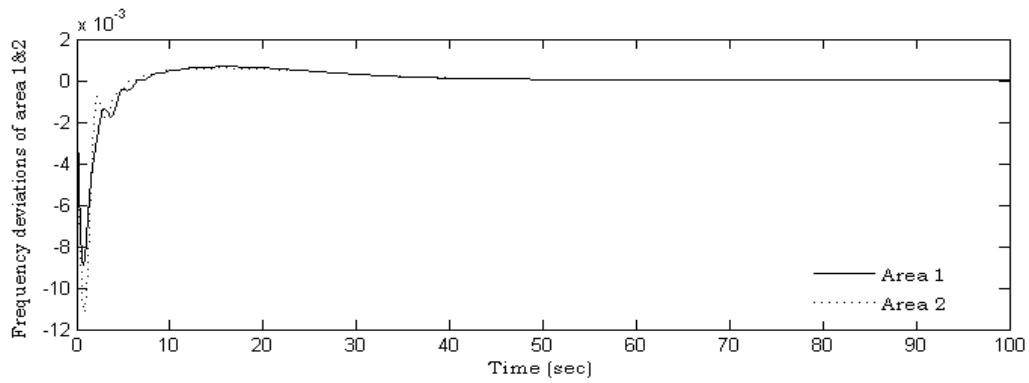


Figure 3. Frequency deviations of both areas during base case

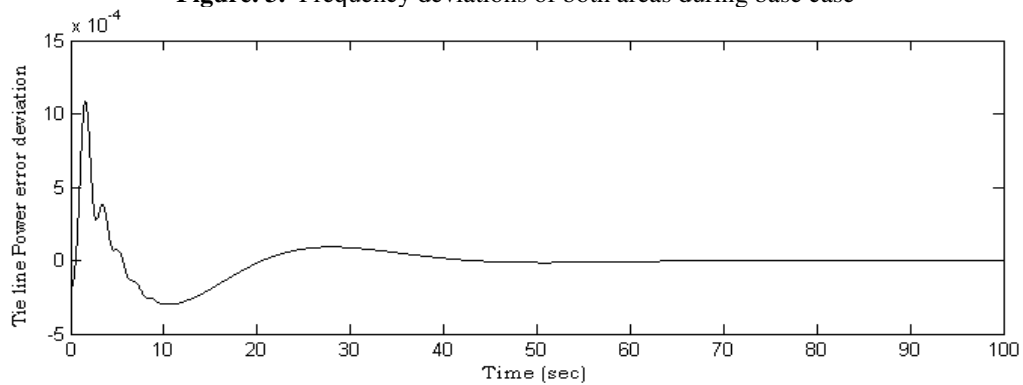


Figure 4. Tie line power error deviation

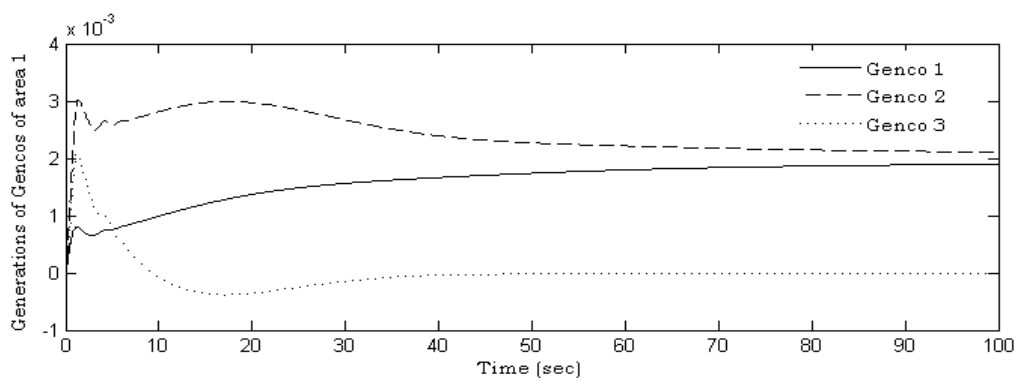


Figure 5. Generation of Gencos in area 1

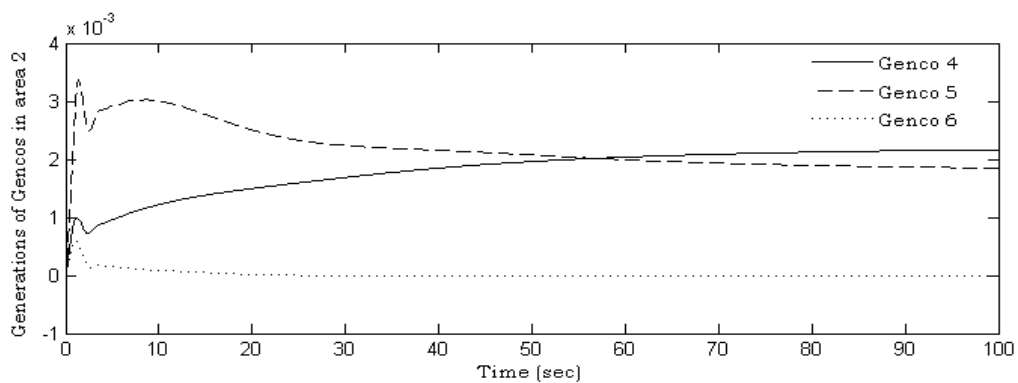


Figure 6. Generation of Gencos in area 2

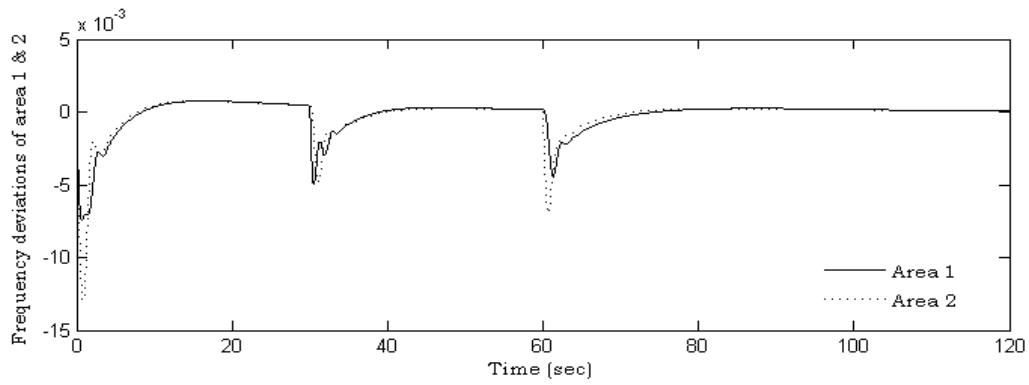


Figure. 7. Frequency deviations of both areas during contract violation

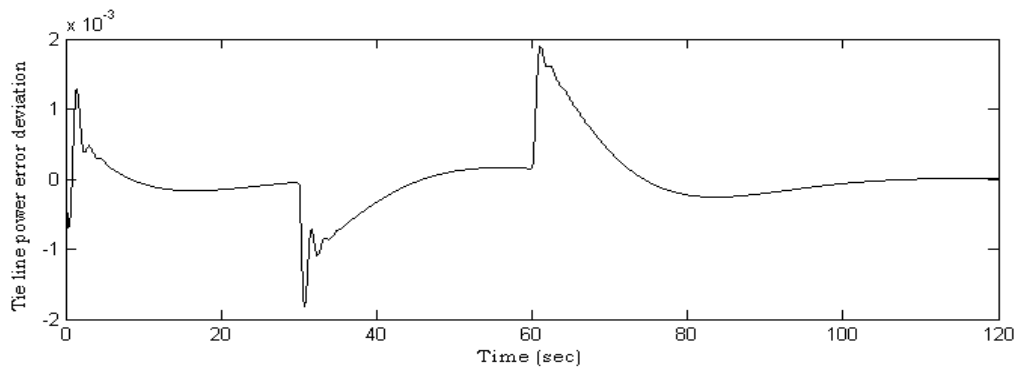


Figure. 8. Tie line power error deviation during contract violation

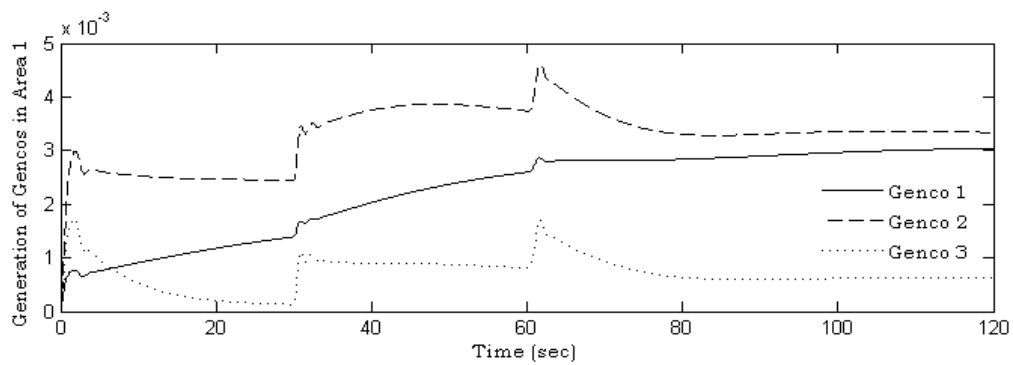


Figure. 9. Generation of Gencos in area 1 during contract violation

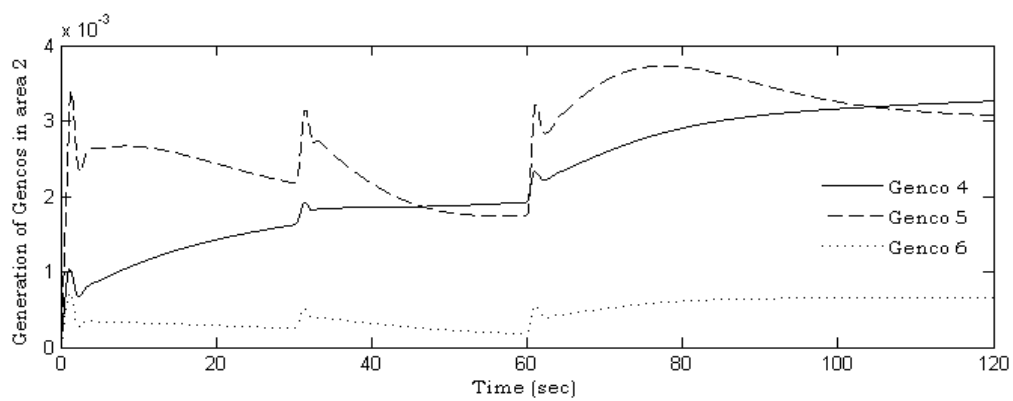


Figure. 10. Generation of Gencos in area 2 during contract violation

V. CONCLUSIONS

AGC provides a relatively, yet extremely effective method of adjusting generation to minimize frequency deviations and regulate tie-line flows. This important role of adjusting generation also continues in restructured electricity markets. Bilateral contracts can exist between Discos in one area and Gencos in other areas. The concept of Disco Participation Matrix has been used in this work which provides a compact yet precise way of summarizing bilateral contracts in a multi area hydrothermal system under restructured scenario. Load following has been examined and it was noted that the generating unit under load following generates the required contracted power in the steady state and also that, at least one generating unit in each area must be under AGC to draw the frequency deviation and tie power error to zero in the steady state. The modeling of AGC in a restructured environment must take into account the information flow relating to bilateral contracts.

APPENDIX

$R = 2.4$ Hz/p.u.MW; $D = 8.33 \times 10^{-3}$ p.u. MW/Hz; $K_g = 1$; $T_g = 0.08$ sec; $K_t = 1$; $T_t = 0.3$ sec; $K_r = 0.5$; $T_r = 10$ sec; $T_1, T_2, T_R = 41.6, 0.513, 5$ sec; $T_w = 1$ sec; $K_p = 120$ Hz/p.u. MW; $T_p = 20$ sec; $B = 0.425$ p.u. MW/Hz

REFERENCES

- [1] C. Concordia and L.K.Kirchmayer, "Tie-Line Power and Frequency Control of Electric Power System - Part II", AIEE Transaction, vol. 73, Part- 111-A, April 1954, pp. 133-146.
- [2] M.L.Kothari, B.L.Kaul and J.Nanda, "Automatic Generation Control of Hydro- Thermal system", journal of Institute of Engineers(India), vol.61, pt EL2,oct 1980, pp85-91.
- [3] J.Nanda, M.L.Kothari, P.S.Satsangi, "Automatic Generation Control of an Interconnected hydrothermal system in Continuous and Discrete modes considering Generation Rate Constraints", IEE Proc., vol. 130, pt D, No.1 Jan. 1983, pp 455- 460.
- [4] Robert P. Schulte, "Automatic generation Control modification for present demands on interconnected power systems", IEEE Trans. On Power Systems, August 1996,pp. 1286- 1291.
- [5] Jayant Kumar, Kah-Koeng and Gerald Sheble, "AGC simulator for price based operation Part1", IEEE Transactions on Power Systems, vol.12,no.2, May 1997,pp. 527-532.
- [6] Jayant Kumar, Kah-Hoeng and Gerald Sheble, "AGC simulator for price based operation part- 2", IEEE Transactions on Power Systems, Vol.12, no. 2, May1997, pp 533-538.
- [7] Bjorn H.Bakken and OvesGrande, "Automatic generation control in a deregulated environment", IEEE Transactions on Power Systems, vol.13, no.4, Nov1998,pp. 1401-1406.
- [8] Preghnesh Bhatt, S.P. Ghoshal, and Ranjit Roy-" Optimized multi area AGC simulation in restructured power systems"- International Journal of Electrical Power & Energy Systems, Volume 32,Issue 4, May 2010, Pages 311-322.
- [9] Emilia Nobile, Anjan Bose and Kevin Tomsovic "Feasibility of a bilateral market for load following", IEEE Transactions on Power systems, Vol. 16, No. 4, November 2001,pp.782-787.
- [10] D. Rerkpreedapong and A. Feliachi, "Decentralized load frequency control for load following services," in Proc. IEEE Power Eng. Soc. Winter Meeting, Jan. 2002, pp. 1252–1257.
- [11] Enrico De Tuglie and Francesco Torelli "Load following control schemes for Deregulated energy markets", IEEE Transactions on Power systems, Vol. 21, No. 4, November 2006,pp.1691-1698.
- [12] "Dynamic Models for steam and Hydro Turbines in Power system studies", IEEE committee report. Transactions in Power Apparatus &Systems Vol.92,No.6,Nov./Dec.1973,pp.1904-915.
- [13] Manoranjan Parida and J. Nandal " Automatic Generation Control of a Hydro-Thermal System in Deregulated Environment", Proceedings of the Eighth International Conference on Electrical Machines and Systems, vol 2,Septmeber 2005 , page 942-947.

Authors Profile

A. Suresh Babu received his B.Tech (EEE) degree from JNTUCE, Anantapur, Andhra Pradesh, India in 2003, M.Tech in Advanced Power System from JNTUCE, Kakinada, Andhra Pradesh, India. He is currently working as Associate Professor in EEE Department at SSNEC, Ongole, Andhra Pradesh, India. His areas of interest are Power System operation and control, control systems and Power distribution systems.



Ch. Sai Babu received the B.E from Andhra University (Electrical & Electronics Engineering), M.Tech in Electrical Machines and Industrial Drives from REC, Warangal and PhD in Reliability Studies of HVDC Converters from JNTU, Hyderabad. Currently he is working as a Professor in Dept. of EEE & Director-Admissions in JNTUK, Kakinada. He has published several National and International Journals and Conferences. His area of interest is Power Electronics and Drives, Power System Reliability, HVDC Converter Reliability, Optimization of Electrical Systems and Real Time Energy Management.



S. Sivanaga Raju: He received B.E from Andhra University and M.Tech., degree in 2000 from IIT, Kharagpur and did his Ph.D from Jawaharlal Nehru Technological University, Anantapur, India in 2004. He is presently working as Associate Professor HOD-EEE in J.N.T.U.College of Engineering Kakinada(Autonomous) Kakinada , Andhra Pradesh, India. He received two national awards (Pandit Madan Mohan Malaviya memorial Prize and best paper prize award from the Institute of Engineers(India) for the year 2003-04. He is referee for IEEE journals. He has around 75 National and International journals in his credit. His research interest includes Power distribution Automation and Power System operation and control.

